

Approximate Computations in Commutative Algebra

Martin Kreuzer

Fachbereich Mathematik

Universität Dortmund

`martin.kreuzer@uni-dortmund.de`

An approximate lecture, given at the

Fifth Int. CoCoA School

Hagenberg, June 22, 2007

Contents

Contents

1. Approximate Data and Polynomials

Contents

1. Approximate Data and Polynomials
2. Approximate Vanishing Ideals

Contents

1. Approximate Data and Polynomials
2. Approximate Vanishing Ideals
3. The Singular Value Decomposition

Contents

1. Approximate Data and Polynomials
2. Approximate Vanishing Ideals
3. The Singular Value Decomposition
4. The BM-Algorithm

Contents

1. Approximate Data and Polynomials
2. Approximate Vanishing Ideals
3. The Singular Value Decomposition
4. The BM-Algorithm
5. The ABM-Algorithm

Contents

1. Approximate Data and Polynomials
2. Approximate Vanishing Ideals
3. The Singular Value Decomposition
4. The BM-Algorithm
5. The ABM-Algorithm
6. We Need an Example

1 – Approximate Data and Polynomials

1 – Approximate Data and Polynomials

Ralph W. Emerson:

1 – Approximate Data and Polynomials

Ralph W. Emerson: I hate quotations.
Tell me what you know.

1 – Approximate Data and Polynomials

Ralph W. Emerson: I hate quotations.
Tell me what you know.

$P = \mathbb{R}[x_1, \dots, x_n]$ polynomial ring over the real number field

$\mathbb{X} = \{p_1, \dots, p_s\}$ finite set of points in \mathbb{R}^n

The map $\text{eval} : P \longrightarrow \mathbb{R}^s$ given by $f \mapsto (f(p_1), \dots, f(p_s))$ is called the **evaluation map** associated to \mathbb{X} .

The ideal $I_{\mathbb{X}} = \ker(\text{eval})$ is called the **vanishing ideal** of \mathbb{X} .

1 – Approximate Data and Polynomials

Ralph W. Emerson: I hate quotations.
Tell me what you know.

$P = \mathbb{R}[x_1, \dots, x_n]$ polynomial ring over the real number field

$\mathbb{X} = \{p_1, \dots, p_s\}$ finite set of points in \mathbb{R}^n

The map $\text{eval} : P \longrightarrow \mathbb{R}^s$ given by $f \mapsto (f(p_1), \dots, f(p_s))$ is called the **evaluation map** associated to \mathbb{X} .

The ideal $I_{\mathbb{X}} = \ker(\text{eval})$ is called the **vanishing ideal** of \mathbb{X} .

The Gretchen Question:

1 – Approximate Data and Polynomials

Ralph W. Emerson: I hate quotations.
Tell me what you know.

$P = \mathbb{R}[x_1, \dots, x_n]$ polynomial ring over the real number field

$\mathbb{X} = \{p_1, \dots, p_s\}$ finite set of points in \mathbb{R}^n

The map $\text{eval} : P \longrightarrow \mathbb{R}^s$ given by $f \mapsto (f(p_1), \dots, f(p_s))$ is called the **evaluation map** associated to \mathbb{X} .

The ideal $I_{\mathbb{X}} = \ker(\text{eval})$ is called the **vanishing ideal** of \mathbb{X} .

The Gretchen Question: What happens if the points of \mathbb{X} are only empirical points, e.g. points whose coordinates are derived from measured data?

In the following we let $-\varepsilon < 0$ be a given **threshold number**.

In the following we let $-\varepsilon < \mathbf{0}$ be a given **threshold number**.

A polynomial $f \in P$ is said to **vanish ε -approximately** at a point $p \in \mathbb{R}^n$ if $|f(p)| < \varepsilon$.

In the following we let $\varepsilon > 0$ be a given **threshold number**.

A polynomial $f \in P$ is said to **vanish ε -approximately** at a point $p \in \mathbb{R}^n$ if $|f(p)| < \varepsilon$.

And here is the (hori-)**crux** of the matter: the polynomials which vanish ε -approximately at \mathbb{X} **do not form an ideal**.

Example 1.1 If $|f(p)| = 0.001 < \varepsilon = 0.1$ then $|(1000f)(p)| = 1 > \varepsilon$.

Hence the question whether f vanishes at p or not depends on the size of f , i.e. we need a **metric** on P .

Definition 1.2 Let $f = a_1t_1 + \cdots + a_st_s \in P$, where $a_1, \dots, a_s \in \mathbb{R} \setminus \{0\}$ and $t_1, \dots, t_s \in \mathbb{T}^n$.

Then the number $\|f\| = \|(a_1, \dots, a_s)\|$ is called the (Euclidean) **norm** (or the **size**) of f .

Clearly, this definition turns P into a normed vector space.

Definition 1.2 Let $f = a_1 t_1 + \cdots + a_s t_s \in P$, where $a_1, \dots, a_s \in \mathbb{R} \setminus \{0\}$ and $t_1, \dots, t_s \in \mathbb{T}^n$.

Then the number $\|f\| = \|(a_1, \dots, a_s)\|$ is called the (Euclidean) **norm** (or the **size**) of f .

Clearly, this definition turns P into a normed vector space.

BIG TROUBLE in little Hagenberg!

A very small polynomial **always** vanishes ε -approximately at \mathbb{X} !

Definition 1.2 Let $f = a_1 t_1 + \cdots + a_s t_s \in P$, where $a_1, \dots, a_s \in \mathbb{R} \setminus \{0\}$ and $t_1, \dots, t_s \in \mathbb{T}^n$.

Then the number $\|f\| = \|(a_1, \dots, a_s)\|$ is called the (Euclidean) **norm** (or the **size**) of f .

Clearly, this definition turns P into a normed vector space.

BIG TROUBLE in little Hagenberg!

A very small polynomial **always** vanishes ε -approximately at \mathbb{X} !

Hence it is reasonable to consider the condition that polynomials $f \in P$ with $\|f\| = 1$ vanish ε -approximately at p .

2 – Approximate Vanishing Ideals

Definition 2.1 An ideal $I \subseteq P$ is called an **ε -approximate vanishing ideal** of \mathbb{X} if there exists a system of generators $\{f_1, \dots, f_r\}$ of I such that $\|f_i\| = 1$ and f_i vanishes ε -approximately at \mathbb{X} for $i = 1, \dots, r$.

2 – Approximate Vanishing Ideals

Definition 2.1 An ideal $I \subseteq P$ is called an ε -**approximate vanishing ideal** of \mathbb{X} if there exists a system of generators $\{f_1, \dots, f_r\}$ of I such that $\|f_i\| = 1$ and f_i vanishes ε -approximately at \mathbb{X} for $i = 1, \dots, r$.

More trouble ahead!

2 – Approximate Vanishing Ideals

Definition 2.1 An ideal $I \subseteq P$ is called an ε -**approximate vanishing ideal** of \mathbb{X} if there exists a system of generators $\{f_1, \dots, f_r\}$ of I such that $\|f_i\| = 1$ and f_i vanishes ε -approximately at \mathbb{X} for $i = 1, \dots, r$.

More trouble ahead!

- Approximate vanishing ideals are **not at all unique**. They are not necessarily zero-dimensional either!

2 – Approximate Vanishing Ideals

Definition 2.1 An ideal $I \subseteq P$ is called an ε -approximate **vanishing ideal** of \mathbb{X} if there exists a system of generators $\{f_1, \dots, f_r\}$ of I such that $\|f_i\| = 1$ and f_i vanishes ε -approximately at \mathbb{X} for $i = 1, \dots, r$.

More trouble ahead!

- Approximate vanishing ideals are **not at all unique**. They are not necessarily zero-dimensional either!
- If the coordinates of the points are very small, **every** polynomial of norm 1 in $\langle x_1, \dots, x_n \rangle$ vanishes at \mathbb{X} .

2 – Approximate Vanishing Ideals

Definition 2.1 An ideal $I \subseteq P$ is called an ε -**approximate vanishing ideal** of \mathbb{X} if there exists a system of generators $\{f_1, \dots, f_r\}$ of I such that $\|f_i\| = 1$ and f_i vanishes ε -approximately at \mathbb{X} for $i = 1, \dots, r$.

More trouble ahead!

- Approximate vanishing ideals are **not at all unique**. They are not necessarily zero-dimensional either!
- If the coordinates of the points are very small, **every** polynomial of norm 1 in $\langle x_1, \dots, x_n \rangle$ vanishes at \mathbb{X} .

In the following we ignore these problems and simply compute an approximate vanishing ideal of \mathbb{X} .

2 – Approximate Vanishing Ideals

Definition 2.1 An ideal $I \subseteq P$ is called an ε -**approximate vanishing ideal** of \mathbb{X} if there exists a system of generators $\{f_1, \dots, f_r\}$ of I such that $\|f_i\| = 1$ and f_i vanishes ε -approximately at \mathbb{X} for $i = 1, \dots, r$.

More trouble ahead!

- Approximate vanishing ideals are **not at all unique**. They are not necessarily zero-dimensional either!
- If the coordinates of the points are very small, **every** polynomial of norm 1 in $\langle x_1, \dots, x_n \rangle$ vanishes at \mathbb{X} .

In the following we ignore these problems and simply compute an approximate vanishing ideal of \mathbb{X} .

It's kind of fun to do the impossible. (Walt Disney)

3 – The Singular Value Decomposition

3 – The Singular Value Decomposition

Theorem 3.1 *Let $A \in \text{Mat}_{m,n}(\mathbb{R})$.*

There are orthogonal matrices $U \in \text{Mat}_{m,m}(\mathbb{R})$ and $V \in \text{Mat}_{n,n}(\mathbb{R})$ and a matrix $S \in \text{Mat}_{m,n}(\mathbb{R})$ of the form $S = \begin{pmatrix} \mathcal{D} & 0 \\ 0 & 0 \end{pmatrix}$ such that

$$A = U \cdot S \cdot V^{\text{tr}} = U \cdot \begin{pmatrix} \mathcal{D} & 0 \\ 0 & 0 \end{pmatrix} \cdot V^{\text{tr}}$$

where $\mathcal{D} = \text{diag}(s_1, \dots, s_r)$ is a diagonal matrix.

In this decomposition, it is possible to achieve:

1. $s_1 \geq s_2 \geq \cdots \geq s_r > 0$. The numbers s_1, \dots, s_r depend only on \mathcal{A} and are called the **singular values** of \mathcal{A} .
2. The number r is the rank of \mathcal{A} .
3. The matrices \mathcal{U} and \mathcal{V} have the following interpretation:

first r columns of \mathcal{U}	\equiv	ONB of the column space of \mathcal{A}
last $m - r$ columns of \mathcal{U}	\equiv	ONB of the kernel of \mathcal{A}^{tr}
first r columns of \mathcal{V}	\equiv	ONB of the row space of \mathcal{A}
	\equiv	ONB of the column space of \mathcal{A}^{tr}
last $n - r$ columns of \mathcal{V}	\equiv	ONB of the kernel of \mathcal{A}

Definition 3.2 Let $\mathcal{A} \in \text{Mat}_{m,n}(\mathbb{R})$, and let $\varepsilon > 0$ be given. Let $k \in \{1, \dots, r\}$ be chosen such that $s_k > \varepsilon \geq s_{k+1}$. Form the matrix $\tilde{\mathcal{A}} = \mathcal{U} \tilde{\mathcal{S}} \mathcal{V}^{\text{tr}}$ by setting $s_{k+1} = \dots = s_r = 0$ in \mathcal{S} . Then $\tilde{\mathcal{A}}$ is called the **singular value truncation** of \mathcal{A} at ε .

Definition 3.2 Let $\mathcal{A} \in \text{Mat}_{m,n}(\mathbb{R})$, and let $\varepsilon > 0$ be given. Let $k \in \{1, \dots, r\}$ be chosen such that $s_k > \varepsilon \geq s_{k+1}$. Form the matrix $\tilde{\mathcal{A}} = \mathcal{U} \tilde{\mathcal{S}} \mathcal{V}^{\text{tr}}$ by setting $s_{k+1} = \dots = s_r = 0$ in \mathcal{S} . Then $\tilde{\mathcal{A}}$ is called the **singular value truncation** of \mathcal{A} at ε .

Corollary 3.3 Let $\tilde{\mathcal{A}}$ be the singular value truncation of \mathcal{A} at ε .

1. $\|\mathcal{A} - \tilde{\mathcal{A}}\| = s_{k+1} = \min\{\|\mathcal{A} - \mathcal{B}\| : \text{rank}(\mathcal{B}) \leq k\}$
2. The vector subspace $\text{apker}(\mathcal{A}, \varepsilon) = \ker(\tilde{\mathcal{A}})$ is the largest dimensional kernel of a matrix whose Euclidean distance from \mathcal{A} is at most ε . It is called the **ε -approximate kernel** of \mathcal{A} .
3. The last $n - k$ columns v_{k+1}, \dots, v_n of \mathcal{V} are an ONB of $\text{apker}(\mathcal{A}, \varepsilon)$. They satisfy $\|\mathcal{A}v_i\| < \varepsilon$.

4 – The BM-Algorithm

Let $\mathbb{X} = \{p_1, \dots, p_s\} \subseteq \mathbb{R}^n$ and σ a degree compatible term ordering.

1. Let $G = \emptyset$, $\mathcal{O} = \{1\}$, $\mathcal{M} = (1, \dots, 1)$, and $d = 0$.
2. Increase d by one. Let $L = [t_1, \dots, t_\ell]$ be $\mathbb{T}_d^n \setminus \langle \text{LT}_\sigma(G) \rangle$ ordered decreasingly w.r.t. σ . If $L = \emptyset$, return (G, \mathcal{O}) and stop.
3. Append $\text{eval}(t_1), \dots, \text{eval}(t_\ell)$ as new first rows to \mathcal{M} and get a matrix \mathcal{A} . Find a matrix \mathcal{B} whose rows are a basis of $\ker(\mathcal{A}^{\text{tr}})$.
4. Reduce \mathcal{B} to row echelon form and get a matrix $\mathcal{C} = (c_{ij})$.
5. For the columns j of \mathcal{C} containing a pivot element c_{ij} , append the polynomial corresponding to row i to G .
6. For the columns j of \mathcal{C} containing no pivot element, append t_j to \mathcal{O} , append the row $\text{eval}(t_j)$ to \mathcal{M} , and continue with (2).

5 – The ABM-Algorithm

Let $\mathbb{X} = \{p_1, \dots, p_s\} \subseteq [-1, 1]^n$, let σ be a degree compatible term ordering, and let $\varepsilon > \varepsilon' > 0$.

1. Let $G = \emptyset$, $\mathcal{O} = \{1\}$, $\mathcal{M} = (1, \dots, 1)$, and $d = 0$.
2. Increase d by one. Let $L = [t_1, \dots, t_\ell]$ be $\mathbb{T}_d^n \setminus \langle \text{LT}_\sigma(G) \rangle$ ordered decreasingly w.r.t. σ . If $L = \emptyset$, return (G, \mathcal{O}) and stop.
3. Append $\text{eval}(t_1), \dots, \text{eval}(t_\ell)$ as new first rows to \mathcal{M} and get a matrix \mathcal{A} . Using the SVD of \mathcal{A}^{tr} , compute a matrix \mathcal{B} whose rows are a basis of $\text{apker}(\mathcal{A}^{\text{tr}}, \varepsilon)$.
4. Reduce \mathcal{B} to row echelon form. Normalize each row after every reduction step. If at some point a column contains no pivot element of absolute value $> \varepsilon'$ in the untreated rows, replace the corresponding elements by zero. The result is a matrix $\mathcal{C} = (c_{ij})$.

5. For the columns j of \mathcal{C} containing a pivot element c_{ij} , append the polynomial corresponding to row i to G .
6. For the columns j of \mathcal{C} containing no pivot element, append t_j to \mathcal{O} , append the row $\text{eval}(t_j)$ to \mathcal{M} , and continue with (2).

5. For the columns j of \mathcal{C} containing a pivot element c_{ij} , append the polynomial corresponding to row i to G .
6. For the columns j of \mathcal{C} containing no pivot element, append t_j to \mathcal{O} , append the row $\text{eval}(t_j)$ to \mathcal{M} , and continue with (2).

This is an algorithm which computes a pair (G, \mathcal{O}) .

The list G is a unitary minimal σ -Gröbner basis of the ideal $I = \langle G \rangle \subset P$ and satisfies $\|\text{eval}(g)\| < \delta$ for $\delta = \varepsilon\sqrt{\#G} + \varepsilon's\sqrt{s}$ and all $g \in G$.

The list \mathcal{O} contains an order ideal of monomials whose residue classes form an \mathbb{R} -vector space basis of P/I .

5. For the columns j of \mathcal{C} containing a pivot element c_{ij} , append the polynomial corresponding to row i to G .
6. For the columns j of \mathcal{C} containing no pivot element, append t_j to \mathcal{O} , append the row $\text{eval}(t_j)$ to \mathcal{M} , and continue with (2).

This is an algorithm which computes a pair (G, \mathcal{O}) .

The list G is a unitary minimal σ -Gröbner basis of the ideal $I = \langle G \rangle \subset P$ and satisfies $\|\text{eval}(g)\| < \delta$ for $\delta = \varepsilon\sqrt{\#G} + \varepsilon's\sqrt{s}$ and all $g \in G$.

The list \mathcal{O} contains an order ideal of monomials whose residue classes form an \mathbb{R} -vector space basis of P/I .

We have $\dim_{\mathbb{R}}(P/I) \leq s$. **Thus I is a zero-dimensional ideal and a δ -approximate vanishing ideal of \mathbb{X} .**

6 – We Need an Example

6 – We Need an Example

Let us follow the steps of ABM in a concrete case. We consider the set $\mathbb{X} = \{(0.01, 0.01), (0.49, 0), (0.51, 0), (0, 0.99)\}$ and use the threshold numbers $\varepsilon = 0.1$ and $\varepsilon' = 10^{-6}$.

6 – We Need an Example

Let us follow the steps of ABM in a concrete case. We consider the set $\mathbb{X} = \{(0.01, 0.01), (0.49, 0), (0.51, 0), (0, 0.99)\}$ and use the threshold numbers $\varepsilon = 0.1$ and $\varepsilon' = 10^{-6}$.

1. Let $G = \emptyset$, $\mathcal{O} = \{1\}$, $\mathcal{M} = (1, 1, 1, 1)$, and $d = 0$.

6 – We Need an Example

Let us follow the steps of ABM in a concrete case. We consider the set $\mathbb{X} = \{(0.01, 0.01), (0.49, 0), (0.51, 0), (0, 0.99)\}$ and use the threshold numbers $\varepsilon = 0.1$ and $\varepsilon' = 10^{-6}$.

1. Let $G = \emptyset$, $\mathcal{O} = \{1\}$, $\mathcal{M} = (1, 1, 1, 1)$, and $d = 0$.
2. Consider $d = 1$ and $L = [x, y]$.

6 – We Need an Example

Let us follow the steps of ABM in a concrete case. We consider the set $\mathbb{X} = \{(0.01, 0.01), (0.49, 0), (0.51, 0), (0, 0.99)\}$ and use the threshold numbers $\varepsilon = 0.1$ and $\varepsilon' = 10^{-6}$.

1. Let $G = \emptyset$, $\mathcal{O} = \{1\}$, $\mathcal{M} = (1, 1, 1, 1)$, and $d = 0$.
2. Consider $d = 1$ and $L = [x, y]$.

3. We form $\mathcal{A} = \begin{pmatrix} 0.01 & 0.49 & 0.51 & 0 \\ 0.01 & 0 & 0 & 0.99 \\ 1 & 1 & 1 & 1 \end{pmatrix}$. The SVD of \mathcal{A}^{tr} yields

$s_1 = 2.13$, $s_2 = 0.91$ and $s_3 = 0.35$, so no singular value truncation is necessary. We compute $B = (0, 0, 0)$.

4. We get $\mathcal{C} = (0, 0, 0)$.

4. We get $\mathcal{C} = (0, 0, 0)$.

6. Append x, y to \mathcal{O} and get $\mathcal{O} = \{1, x, y\}$. Moreover, let $\mathcal{M} = \mathcal{A}$.

4. We get $\mathcal{C} = (0, 0, 0)$.
6. Append x, y to \mathcal{O} and get $\mathcal{O} = \{1, x, y\}$. Moreover, let $\mathcal{M} = \mathcal{A}$.
2. Consider $d = 2$ and $L = [x^2, xy, y^2]$.

4. We get $\mathcal{C} = (0, 0, 0)$.
6. Append x, y to \mathcal{O} and get $\mathcal{O} = \{1, x, y\}$. Moreover, let $\mathcal{M} = \mathcal{A}$.
2. Consider $d = 2$ and $L = [x^2, xy, y^2]$.

3. We form the matrix $\mathcal{A} =$

$$\begin{pmatrix} 0.0001 & 0.2401 & 0.2601 & 0 \\ 0.0001 & 0 & 0 & 0 \\ 0.0001 & 0 & 0 & 0.9801 \\ 0.01 & 0.49 & 0.51 & 0 \\ 0.01 & 0 & 0 & 0.99 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

and compute SVD of \mathcal{A}^{tr} . We get the singular values $s_1 = 2.22$, $s_2 = 1.21$, $s_3 = 0.40$, and $s_4 = 0.006$. Thus we have to truncate the singular value $s_4 < \varepsilon$. The SVD of $\tilde{\mathcal{A}}^{\text{tr}}$ yields

that the space $\text{apker}(\mathcal{A}^{\text{tr}}, \varepsilon)$ is generated by the rows of

$$\mathcal{B} = \begin{pmatrix} 0.65 & -0.66 & 0.08 & -0.33 & -0.08 & 0.004 \\ 0.07 & -0.10 & -0.70 & -0.02 & 0.70 & -0.007 \\ 0.60 & 0.74 & -0.02 & -0.30 & 0.02 & 0.003 \end{pmatrix}$$

that the space $\text{apker}(\mathcal{A}^{\text{tr}}, \varepsilon)$ is generated by the rows of

$$\mathcal{B} = \begin{pmatrix} 0.65 & -0.66 & 0.08 & -0.33 & -0.08 & 0.004 \\ 0.07 & -0.10 & -0.70 & -0.02 & 0.70 & -0.007 \\ 0.60 & 0.74 & -0.02 & -0.30 & 0.02 & 0.003 \end{pmatrix}$$

4. Now we perform a **normalized** Gaussian reduction on \mathcal{B} and get the matrix

$$\mathcal{C} = \begin{pmatrix} 0.65 & -0.66 & 0.08 & -0.33 & -0.08 & 0.004 \\ 0 & -0.027 & -0.707 & 0.014 & 0.707 & -0.007 \\ 0 & 0 & -0.707 & 0.014 & 0.707 & -0.007 \end{pmatrix}.$$

that the space $\text{apker}(\mathcal{A}^{\text{tr}}, \varepsilon)$ is generated by the rows of

$$\mathcal{B} = \begin{pmatrix} 0.65 & -0.66 & 0.08 & -0.33 & -0.08 & 0.004 \\ 0.07 & -0.10 & -0.70 & -0.02 & 0.70 & -0.007 \\ 0.60 & 0.74 & -0.02 & -0.30 & 0.02 & 0.003 \end{pmatrix}$$

4. Now we perform a **normalized** Gaussian reduction on \mathcal{B} and get the matrix

$$\mathcal{C} = \begin{pmatrix} 0.65 & -0.66 & 0.08 & -0.33 & -0.08 & 0.004 \\ 0 & -0.027 & -0.707 & 0.014 & 0.707 & -0.007 \\ 0 & 0 & -0.707 & 0.014 & 0.707 & -0.007 \end{pmatrix}.$$

5. Append the polynomials

$$g_1 = 0.65x^2 - 0.66xy + 0.08y^2 - 0.33x - 0.08y + 0.004,$$

$$g_2 = -0.027xy - 0.707y^2 + 0.014x + 0.707y - 0.007, \text{ and}$$

$$g_3 = -0.707y^2 + 0.014x + 0.707y - 0.007 \text{ to } G.$$

2. For $d = 3$, we find $L = []$. Hence the result is $G = \{g_1, g_2, g_3\}$ and $\mathcal{O} = \{1, x, y\}$.

2. For $d = 3$, we find $L = []$. Hence the result is $G = \{g_1, g_2, g_3\}$ and $\mathcal{O} = \{1, x, y\}$.

Therefore an approximate vanishing ideal of $\mathbb{X} = \{p_1, p_2, p_3, p_4\}$ is given by $\langle g_1, g_2, g_3 \rangle$ where $g_1 \approx x(x - y - \frac{1}{2})$, $g_2 \approx -0.03xy + g_3$, and $g_3 \approx (-1/\sqrt{2})(y^2 - y)$.

2. For $d = 3$, we find $L = [\]$. Hence the result is $G = \{g_1, g_2, g_3\}$ and $\mathcal{O} = \{1, x, y\}$.

Therefore an approximate vanishing ideal of $\mathbb{X} = \{p_1, p_2, p_3, p_4\}$ is given by $\langle g_1, g_2, g_3 \rangle$ where $g_1 \approx x(x - y - \frac{1}{2})$, $g_2 \approx -0.03xy + g_3$, and $g_3 \approx (-1/\sqrt{2})(y^2 - y)$.

The ideal $\langle g_1, g_3, g_3 \rangle$ is the **exact** vanishing ideal of **three** points!

The two points $(0.49, 0)$ and $(0.51, 0)$ have been combined and count as **one approximate point**.

Corollary 6.1 (The BB Version of ABM)

In the setting of the ABM-Algorithm, replace step 2 by the following step 2'.

*2'. Increase d by one, and let L be the list of all terms of degree d , ordered decreasingly w.r.t. σ . Remove from L all terms which are contained in $\langle \text{LT}_\sigma(g) \mid g \in G \rangle$, **but not the ones in the border of \mathcal{O}** . If $L = \emptyset$, return the pair (G, \mathcal{O}) and stop. Otherwise, let $L = [t_1, \dots, t_\ell]$.*

The resulting algorithm computes a pair (G, \mathcal{O}) . The set $\{\text{LC}_\sigma(g)^{-1}g \mid g \in G\}$ is the \mathcal{O} -border basis of a δ -approximate vanishing ideal $I = \langle G \rangle \subset P$ of \mathbb{X} where $\delta < \varepsilon\sqrt{\#G} + \varepsilon's\sqrt{s}$. The list \mathcal{O} consists of all terms which are not contained in $\text{LT}_\sigma(I)$.

The Last Remark

In the ABM-Algorithm we assumed $\mathbb{X} \subset [-1, 1]^n$. If the initial data points are not in this set, we have to perform **data scaling**.

The Last Remark

In the ABM-Algorithm we assumed $\mathbb{X} \subset [-1, 1]^n$. If the initial data points are not in this set, we have to perform **data scaling**.

Mathematically, the ABM-Algorithm and the stated error estimates are also correct for arbitrary $\mathbb{X} \subseteq \mathbb{R}^n$. But the data scaling provides additional **numerical stability** for the solution.

The Last Remark

In the ABM-Algorithm we assumed $\mathbb{X} \subset [-1, 1]^n$. If the initial data points are not in this set, we have to perform **data scaling**.

Mathematically, the ABM-Algorithm and the stated error estimates are also correct for arbitrary $\mathbb{X} \subseteq \mathbb{R}^n$. But the data scaling provides additional **numerical stability** for the solution.

We considered a real-world example consisting of 2541 points. For both computations, we used $\varepsilon = 0.0001$. The scaled computation took 2 sec., the unscaled one took 4 sec. The following pictures show the mean size of the evaluation vectors of the computed GB polynomials.

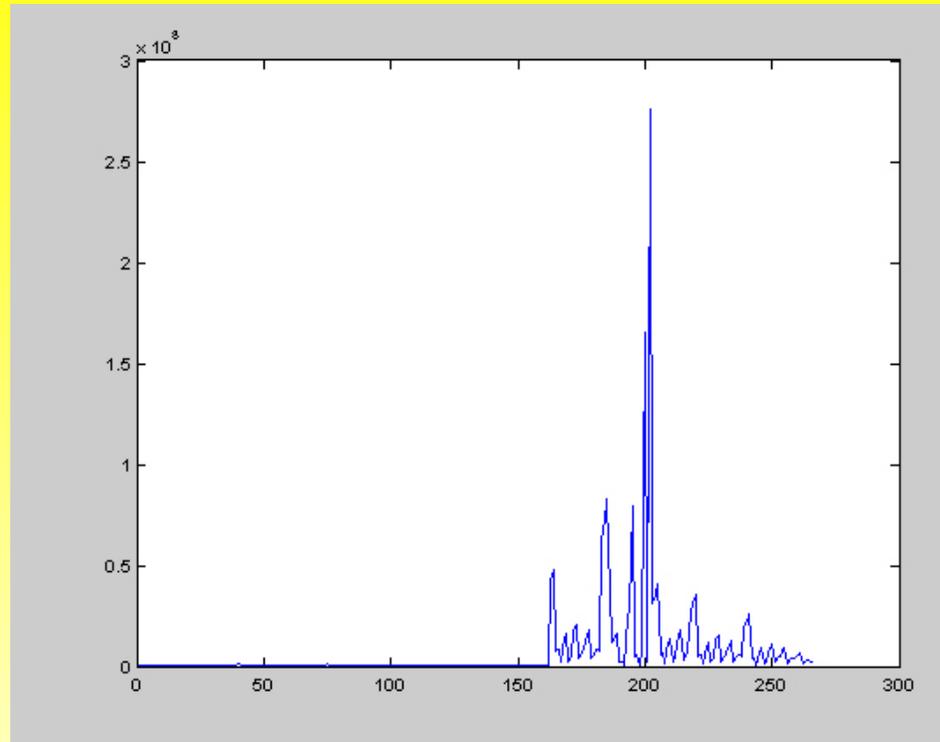


Figure 1: Without Data Scaling

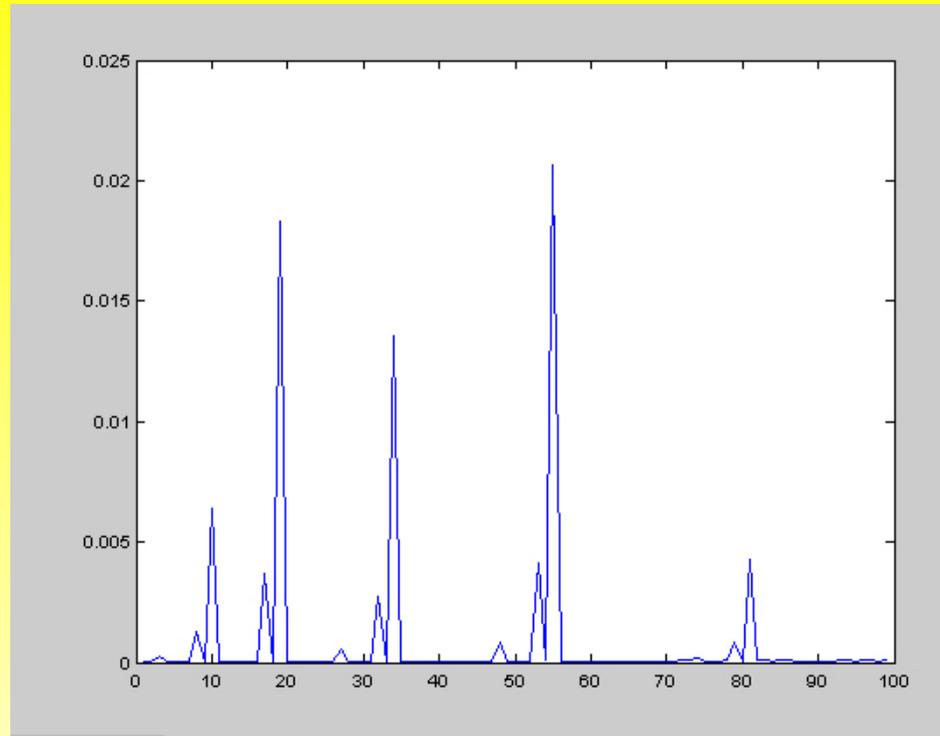


Figure 2: With Data Scaling

Without Data Scaling: 280 GB polynomials

GB mean evaluation error: $2.8 \cdot 10^8$

Without Data Scaling: 280 GB polynomials

GB mean evaluation error: $2.8 \cdot 10^8$

With Data Scaling: 100 GB polynomials

GB mean evaluation error: 0.025

Without Data Scaling: 280 GB polynomials

GB mean evaluation error: $2.8 \cdot 10^8$

With Data Scaling: 100 GB polynomials

GB mean evaluation error: 0.025

The Upshot:

Without Data Scaling: 280 GB polynomials

GB mean evaluation error: $2.8 \cdot 10^8$

With Data Scaling: 100 GB polynomials

GB mean evaluation error: 0.025

The Upshot: Treat your approximate data right!

Then they will treat you *approximately* right!

Without Data Scaling: 280 GB polynomials

GB mean evaluation error: $2.8 \cdot 10^8$

With Data Scaling: 100 GB polynomials

GB mean evaluation error: 0.025

The Upshot: Treat your approximate data right!

Then they will treat you *approximately* right!

Thank you for your attention!